# Why Adversarial Interaction Creates Non-Homogeneous Patterns: A Pseudo-Reaction-Diffusion Model for Turing Instability

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Pseudo-Reaction-Diffusion Model

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### Overview







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Supervised Learning vs Regularized Adversarial Learning



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• Symmetry and homogeneity

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- Breakdown of symmetry and homogeneity

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- Symmetry and homogeneity
- Breakdown of symmetry and homogeneity
- Root cause: Turing instability

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#### Hypothesis

A system in which a generator and a discriminator adversarially interact with each other exhibits Turing-like patterns in the hidden layer and top layer of a two layer generator network with ReLU activation.

## Objectives

• Does it converge? If so, under what circumstance?

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### Objectives

- Does it converge? If so, under what circumstance?
- Why do non-homogeneous patterns emerge?

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## Objectives

- Does it converge? If so, under what circumstance?
- Why do non-homogeneous patterns emerge?
- Why is it important to study such patterns?

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#### Problem Setup

Consider *n* i.i.d. training samples:  $\{(\mathbf{x}_{p}, \mathbf{y}_{p})\}_{p=1}^{n} \subset \mathbb{R}^{d_{in}} \times \mathbb{R}^{d_{out}}$ .

Two layer network with ReLU activation ( $\sigma(.)$ ):

$$f(\boldsymbol{U},\boldsymbol{V},\boldsymbol{x}) = \frac{1}{\sqrt{d_{out}m}} \boldsymbol{V}\sigma(\boldsymbol{U}\boldsymbol{x}).$$
(1)

Here,  $\boldsymbol{U} \in \mathbb{R}^{m \times d_{in}}$  and  $\boldsymbol{V} \in \mathbb{R}^{d_{out} \times m}$ .

Let input data points be represented by  $\mathbf{X} = (\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n) \in \mathbb{R}^{d_{in} \times n}$  and corresponding labels by  $\mathbf{Y} = (\mathbf{y}_1, \mathbf{y}_2, \dots, \mathbf{y}_n) \in \mathbb{R}^{d_{out} \times n}$ .

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### Problem Setup

Supervised learning:

$$\mathcal{L}_{sup}\left(\boldsymbol{U},\boldsymbol{V}\right) = \frac{1}{2} \sum_{p=1}^{n} \left\| \frac{1}{\sqrt{d_{out}m}} \boldsymbol{V}\sigma\left(\boldsymbol{U}\boldsymbol{x}_{p}\right) - \boldsymbol{y}_{p} \right\|_{2}^{2}$$
$$= \frac{1}{2} \left\| \frac{1}{\sqrt{d_{out}m}} \boldsymbol{V}\sigma\left(\boldsymbol{U}\boldsymbol{X}\right) - \boldsymbol{Y} \right\|_{F}^{2}.$$

(2)

Regularized adversarial learning:

$$\mathcal{L}_{aug}\left(\boldsymbol{U},\boldsymbol{V},\boldsymbol{W},\boldsymbol{a}\right) = \underbrace{\frac{1}{2} \left\| \frac{1}{\sqrt{d_{out}m}} \boldsymbol{V}\sigma\left(\boldsymbol{U}\boldsymbol{X}\right) - \boldsymbol{Y} \right\|_{F}^{2}}_{\mathcal{L}_{sup}} - \underbrace{\frac{1}{m\sqrt{d_{out}}} \sum_{p=1}^{n} \boldsymbol{a}^{T}\sigma\left(\boldsymbol{W}\boldsymbol{V}\sigma\left(\boldsymbol{U}\boldsymbol{x}_{p}\right)\right)}_{\mathcal{L}_{adv, D}}$$
(3)  
(3)

# Learning Algorithm

Randomly initialized gradient descent:

$$\frac{du_{jk}}{dt} = -\frac{\partial \mathcal{L}_{aug} \left( \boldsymbol{U}(t), \boldsymbol{V}(t), \boldsymbol{W}(t), \boldsymbol{a}(t) \right)}{\partial u_{jk}(t)},$$
$$\frac{dv_{ij}}{dt} = -\frac{\partial \mathcal{L}_{aug} \left( \boldsymbol{U}(t), \boldsymbol{V}(t), \boldsymbol{W}(t), \boldsymbol{a}(t) \right)}{\partial v_{ij}(t)}$$

for  $i \in [d_{out}]$ ,  $j \in [m]$  and  $k \in [d_{in}]$ .

Equilibrium (ideal condition):  $\frac{du_{jk}}{dt} = \frac{dv_{ij}}{dt} = 0.$  $\epsilon$ -approximate equilibrium:  $\left|\frac{du_{jk}}{dt}\right| < \epsilon$  and  $\left|\frac{dv_{ij}}{dt}\right| < \epsilon$  for a small  $\epsilon$ .

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(4)

# Revisiting Turing's Reaction-Diffusion Model

Governing **Reaction**  $(\mathfrak{R})$  and **Diffusion**  $(\mathfrak{D})$  dynamics:

$$\frac{d\mathbf{u}_{j}}{dt} = \mathfrak{R}_{j}^{\mathbf{u}}(\mathbf{u}_{j},\mathbf{v}_{j}) + \mathfrak{D}_{j}^{\mathbf{u}}(\nabla^{2}\mathbf{u}_{j}), 
\frac{d\mathbf{v}_{j}}{dt} = \mathfrak{R}_{j}^{\mathbf{v}}(\mathbf{u}_{j},\mathbf{v}_{j}) + \mathfrak{D}_{j}^{\mathbf{v}}(\nabla^{2}\mathbf{v}_{j}).$$
(5)

• Turing, A. 1952. The Chemical Basis of Morphogenesis. Phil. Trans. of the Royal Society of London. Series B, Biological Sciences 237(641): 37–72.

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# Simplified Setup: Scalar Network and Training One Layer

Simplified Generator network:

$$f(\boldsymbol{U},\boldsymbol{v},\boldsymbol{x}) = \frac{1}{\sqrt{m}} \sum_{j=1}^{m} v_j \sigma\left(\boldsymbol{u}_j^T \boldsymbol{x}\right) = \frac{1}{\sqrt{m}} \boldsymbol{v}^T \sigma\left(\boldsymbol{U} \boldsymbol{x}\right).$$
(6)

Supervised learning:

$$\mathcal{L}_{sup}\left(\boldsymbol{U},\boldsymbol{v}\right) = \sum_{p=1}^{n} \frac{1}{2} \left( f\left(\boldsymbol{U},\boldsymbol{v},\boldsymbol{x}_{p}\right) - y_{p} \right)^{2}$$
(7)

Regularized adversarial learning:  $\mathcal{L}_{aug}\left( \boldsymbol{U}, \boldsymbol{v}, \boldsymbol{w}, \boldsymbol{a} \right)$ 

$$=\sum_{p=1}^{n}\frac{1}{2}\left(f\left(\boldsymbol{U},\boldsymbol{v},\boldsymbol{x}_{p}\right)-\boldsymbol{y}_{p}\right)^{2}-\frac{1}{\sqrt{m}}\sum_{p=1}^{n}\boldsymbol{a}^{T} \sigma\left(\boldsymbol{w}\left(f\left(\boldsymbol{U},\boldsymbol{v},\boldsymbol{x}_{p}\right)\right)\right)$$
(8)

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**Definition 1.** (Du et al., 2018) Define Gram matrix  $\mathcal{H}^{\infty} \in \mathcal{R}^{n \times n}$ . Each entry of  $\mathcal{H}^{\infty}$  is computed by  $\mathcal{H}_{ij}^{\infty} = \mathbb{E}_{u \sim \mathcal{N}(0,l)} \left[ x_i^T x_j \mathbf{1}_{\left\{ u^T x_i \geq 0, u^T x_j \geq 0 \right\}} \right]$ .

**Assumption 1.** (Du et al., 2018) We assume  $\lambda_0 \triangleq \lambda_{min}(\mathcal{H}^{\infty}) > 0$  which means that  $\mathcal{H}^{\infty}$  is a positive definite matrix.

**Lemma 1.** If we i.i.d initialize  $u_{jk} \sim \mathcal{N}(0,1)$  for  $j \in [m]$  and  $k \in [d_{in}]$ , then with probability at least  $(1 - \delta)$ ,  $u_{jk}$  induces a symmetric and homogeneously distributed matrix U at initialization within a ball of radius  $\zeta \triangleq \frac{2\sqrt{md_{in}}}{\sqrt{2\pi\delta}}$ .

**Remark 1.** Suppose  $\|\mathbf{u}_j - \mathbf{u}_j(0)\|_2 \leq \frac{c\delta\lambda_0}{n^2} \triangleq R$  for some small positive constant *c*. In the current setup, the Gram matrix  $\mathcal{H} \in \mathbb{R}^{n \times n}$  defined by

$$\mathcal{H}_{ij} = \mathbf{x}_i^T \mathbf{x}_j \frac{1}{m} \sum_{r=1}^m \mathbb{1}_{\left\{\mathbf{u}_r^T \mathbf{x}_i \ge 0, \mathbf{u}_r^T \mathbf{x}_j \ge 0\right\}}$$
satisfies  $\|\mathcal{H} - \mathcal{H}(0)\|_2 \le \frac{\lambda_0}{4}$  and  $\lambda_{min}(\mathcal{H}) \ge \frac{\lambda_0}{2}$ .

**Remark 2.** With Gram matrix  $\mathcal{H}(t)$ , the prediction dynamics,  $z(t) = f(\mathbf{U}(t), \mathbf{v}(t), \mathbf{x})$  are governed by the following ODE:  $\frac{d\mathbf{z}(t)}{dt} = \mathcal{H}(t)(\mathbf{y} - \mathbf{z}(t)).$ 

**Remark 3.** For  $\lambda_{min}(\mathcal{H}(t)) \geq \frac{\lambda_0}{2}$ , we have

$$\|\boldsymbol{z}(t) - \boldsymbol{y}\|_2 \leq \exp\left(-\frac{\lambda_0}{2}t\right) \|\boldsymbol{z}(0) - \boldsymbol{y}\|_2.$$

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Pseudo-Reaction-Diffusion Model

#### Theorem (Symmetry and Homogeneity)

Suppose Assumption 1 holds. Let us i.i.d. initialize  $u_j \sim \mathcal{N}(0, I)$  and sample  $v_j$  uniformly from  $\{+1, -1\}$  for all  $j \in [m]$ . If we choose  $||x_p||_2 = 1$  for  $p \in [n]$ , then we obtain the following with probability at least  $1 - \delta$ :

$$egin{aligned} & \left\| oldsymbol{u}_{j}(t) - oldsymbol{u}_{j}(0) 
ight\|_{2} \leq \mathcal{O}\left( rac{n^{3/2}}{\sqrt{m}\lambda_{0}\delta} 
ight), \ & \left\| oldsymbol{U}(t) - oldsymbol{U}(0) 
ight\|_{F} \leq \mathcal{O}\left( rac{n^{3/2}}{\lambda_{0}\delta} 
ight). \end{aligned}$$

Pseudo-Reaction-Diffusion Model

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#### Theorem (Breakdown of Symmetry and Homogeneity)

Suppose Assumption 1 holds. Let us i.i.d. initialize  $u_j, w_r \sim \mathcal{N}(0, I)$  and sample  $v_j, a_r$  uniformly from  $\{+1, -1\}$  for  $j, r \in [m]$ . Let  $||x_p||_2 = 1$  for all  $p \in [n]$ . If we choose  $||w||_2 \leq L \leq \mathcal{O}\left(\frac{\epsilon\sqrt{m}}{\kappa n\sqrt{2\log(2/\delta)}}\right)$ ,  $\kappa = \mathcal{O}(\kappa^{\infty})$  where  $\kappa^{\infty}$  denotes the condition number of  $\mathcal{H}^{\infty}$ , and define  $\mu \triangleq \frac{Ln\sqrt{2\log(2/\delta)}}{\sqrt{m}}$ , then with probability at least  $1 - \delta$ , we obtain the following:

$$\begin{split} \|\boldsymbol{u}_{j}(t) - \boldsymbol{u}_{j}(0)\|_{2} &\leq \mathcal{O}\left(\frac{n^{3/2}}{\sqrt{m}\lambda_{0}\delta} + \left(\frac{\mu\left(1 + \kappa\sqrt{n}\right)}{\sqrt{m}}\right)t\right), \\ \|\boldsymbol{U}(t) - \boldsymbol{U}(0)\|_{F} &\leq \mathcal{O}\left(\frac{n^{3/2}}{\lambda_{0}\delta} + \mu\left(1 + \kappa\sqrt{n}\right)t\right). \end{split}$$

# Reaction With Diffusion: Proof Sketch

Gradient Flow:

$$\left\|\frac{d\boldsymbol{u}_{j}(s)}{ds}\right\|_{2} = \left\|\frac{\partial \mathcal{L}_{aug}\left(\boldsymbol{U},\boldsymbol{v},\boldsymbol{w},\boldsymbol{a}\right)}{\partial \boldsymbol{u}_{j}(s)}\right\|_{2}$$

$$= \left\|\frac{\partial \mathcal{L}_{sup}\left(\boldsymbol{U},\boldsymbol{v}\right)}{\partial \boldsymbol{u}_{j}(s)} - \frac{\partial}{\partial \boldsymbol{u}_{j}(s)}\sum_{p=1}^{n}g\left(\boldsymbol{w},\boldsymbol{a},\boldsymbol{z}_{p}\right)\right\|_{2} \qquad (9)$$

$$\leq \underbrace{\left\|\frac{\partial \mathcal{L}_{sup}\left(\boldsymbol{U},\boldsymbol{v}\right)}{\partial \boldsymbol{u}_{j}(s)}\right\|_{2}}_{\text{Triangle inequality}} + \left\|\frac{\partial}{\partial \boldsymbol{u}_{j}(s)}\sum_{p=1}^{n}g\left(\boldsymbol{w},\boldsymbol{a},\boldsymbol{z}_{p}\right)\right\|_{2}.$$

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Gradient Flow:

$$\left\|\frac{d\boldsymbol{u}_{j}(s)}{ds}\right\|_{2} = \left\|\frac{\partial\mathcal{L}_{aug}\left(\boldsymbol{U},\boldsymbol{v},\boldsymbol{w},\boldsymbol{a}\right)}{\partial\boldsymbol{u}_{j}(s)}\right\|_{2}$$

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$$\leq \left\|\frac{\partial\mathcal{L}_{sup}\left(\boldsymbol{U},\boldsymbol{v}\right)}{\partial\boldsymbol{u}_{j}(s)}\right\|_{2} + \left\|\frac{\partial}{\partial\boldsymbol{u}_{j}(s)}\sum_{p=1}^{n}g\left(\boldsymbol{w},\boldsymbol{a},\boldsymbol{z}_{p}\right)\right\|_{2} \qquad (10)$$
Triangle inequality

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**Lemma 2.** In contrast to **Remark 2**, the prediction dynamics in adversarial regularization are governed by the following ODE:

$$\frac{d\boldsymbol{z}(t)}{dt} = \mathcal{H}(t)\left(\boldsymbol{y} - \boldsymbol{z}(t)\right) + \mathcal{H}(t)\nabla_{\boldsymbol{z}(t)}g(\boldsymbol{w}(t), \boldsymbol{a}(t), \boldsymbol{z}(t)).$$
(11)

**Lemma 3.** (Hoeffding's inequality, two sided (vershynin et al.)) Suppose  $\mathbf{a} = (a_1, a_2, \ldots, a_m) \in \{\pm 1\}^m$  be a collection of independent symmetric Bernoulli random variables, and  $\mathbf{w} = (w_1, w_2, \ldots, w_m) \in \mathbb{R}^m$ . Then, for any t > 0, we have

$$\mathbb{P}\left\{\left|\sum_{r=1}^{m} a_r w_r\right| \ge t\right\} \le 2 \exp\left(-\frac{t^2}{2 \|\boldsymbol{w}\|_2^2}\right).$$
(12)

**Lemma 4.** Suppose Assumption 1 holds. If we denote  $\lambda_{\max}(\mathcal{H}^{\infty})$  by  $\lambda_1^{\infty}$ , then  $\lambda_{\max}(\mathcal{H}) \leq \frac{\lambda_1}{2} \triangleq \lambda_1^{\infty} + \frac{\lambda_0}{2}$ .

The distance from true labels can be bounded by

$$\frac{d}{dt} \|\mathbf{z}(t) - \mathbf{y}\|_{2}^{2} = 2 \left\langle \mathbf{z}(t) - \mathbf{y}, \frac{d\mathbf{z}(t)}{dt} \right\rangle$$

$$= 2 \left\langle \mathbf{z}(t) - \mathbf{y}, -\mathcal{H}(t) \left( \mathbf{z}(t) - \mathbf{y} \right) \right\rangle$$

$$+ 2 \left\langle \mathbf{z}(t) - \mathbf{y}, \mathcal{H}(t) \nabla_{\mathbf{z}(t)} g(\mathbf{w}(t), \mathbf{a}(t), \mathbf{z}(t)) \right\rangle$$
(13)

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$$+ 2 \left\langle \mathbf{z}(t) - \mathbf{y}, \mathcal{H}(t) \nabla_{\mathbf{z}(t)} g(\mathbf{w}(t), \mathbf{a}(t), \mathbf{z}(t)) \right\rangle$$
(13)

Since  $\lambda_{\min}(\mathcal{H}) \geq \frac{\lambda_0}{2}$  (**Remark 1**) and  $\lambda_{\max}(\mathcal{H}) \leq \frac{\lambda_1}{2}$  (Lemma 4), we get

$$\frac{d}{dt} \|\boldsymbol{z}(t) - \boldsymbol{y}\|_{2}^{2} \leq -\lambda_{0} \|\boldsymbol{z}(t) - \boldsymbol{y}\|_{2}^{2} + \lambda_{1} \langle \boldsymbol{z}(t) - \boldsymbol{y}, \nabla_{\boldsymbol{z}(t)} \boldsymbol{g}(\boldsymbol{w}(t), \boldsymbol{a}(t), \boldsymbol{z}(t)) \rangle$$
(14)

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Upon simplification using Lemma 3,

$$\frac{d}{dt} \left\| \boldsymbol{z}(t) - \boldsymbol{y} \right\|_{2}^{2} \leq -\lambda_{0} \left\| \boldsymbol{z}(t) - \boldsymbol{y} \right\|_{2}^{2} + \lambda_{1} \mu \left\| \boldsymbol{z}(t) - \boldsymbol{y} \right\|_{2}$$
(15)

For simplicity, let us suppose  $\psi = \| \mathbf{z}(t) - \mathbf{y} \|_2^2$ . Now,

$$\frac{d\psi}{dt} \le -\lambda_0 \psi + \lambda_1 \mu \psi^{1/2} \tag{16}$$

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$$\frac{d\psi}{dt} \le -\lambda_0 \psi + \lambda_1 \mu \psi^{1/2} \tag{16}$$

Bernoulli Differential Equation (BDE) (Bernoulli, 1695)

$$rac{dx(t)}{dt} = -P(t)x(t) + Q(t)x^n(t) ext{ for } n \in \mathbb{R} ackslash \{0,1\}$$

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Exact solution of the BDE:

$$\|\boldsymbol{z}(t) - \boldsymbol{y}\|_{2} \leq (\|\boldsymbol{z}(0) - \boldsymbol{y}\|_{2} - \kappa\mu) \exp\left(-\frac{\lambda_{0}}{2}t\right) + \kappa\mu.$$
(17)

From warm-up exercise, we know for  $0 \le s \le t$ ,

$$\begin{aligned} \left\| \frac{\partial \mathcal{L}_{sup} \left( \boldsymbol{U}, \boldsymbol{v} \right)}{\partial \boldsymbol{u}_{j}(s)} \right\|_{2} &\leq \frac{\sqrt{n}}{\sqrt{m}} \left\| \boldsymbol{z}(s) - \boldsymbol{y} \right\|_{2} \\ &\leq \frac{\sqrt{n}}{\sqrt{m}} \left( \| \boldsymbol{z}(0) - \boldsymbol{y} \|_{2} - \kappa \mu \right) \exp\left( -\frac{\lambda_{0}}{2} t \right) + \frac{\sqrt{n}}{\sqrt{m}} \kappa \mu. \end{aligned}$$

$$\tag{18}$$

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### Pseudo-Reaction-Diffusion Model

Governing Dynamics:

$$\frac{d\boldsymbol{u}_j}{dt} = \Re_j^{\boldsymbol{u}}\left(\boldsymbol{u}_j, \boldsymbol{v}_j\right) + \mathfrak{D}_j^{\boldsymbol{u}}\left(\boldsymbol{u}_j\right)$$
(19)

Reaction Dynamics:

$$\mathfrak{R}_{j}^{\boldsymbol{\mu}}\left(\boldsymbol{u}_{j}(t),\boldsymbol{v}_{j}(t)\right) \leq \frac{\sqrt{n}}{\sqrt{m}}\left(\|\boldsymbol{z}(0)-\boldsymbol{y}\|_{2}-\kappa\mu\right)\exp\left(-\frac{\lambda_{0}}{2}t\right) + \frac{\sqrt{n}}{\sqrt{m}}\kappa\mu.$$
(20)

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## Pseudo-Reaction-Diffusion Model

Governing Dynamics:

$$\frac{d\mathbf{u}_j}{dt} = \Re_j^{\boldsymbol{u}}\left(\mathbf{u}_j, \mathbf{v}_j\right) + \mathfrak{D}_j^{\boldsymbol{u}}\left(\mathbf{u}_j\right)$$
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(20)

Diffusion Dynamics:

 $\mathfrak{D}_{j}^{\boldsymbol{u}}\left(\boldsymbol{u}_{j}
ight)\leq?$ 

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# Reaction With Diffusion: Diffusion Term

Augmented part:

$$\left\|\frac{d\boldsymbol{u}_{j}(\boldsymbol{s})}{d\boldsymbol{s}}\right\|_{2} \leq \left\|\frac{\partial \mathcal{L}_{sup}\left(\boldsymbol{U},\boldsymbol{v}\right)}{\partial \boldsymbol{u}_{j}(\boldsymbol{s})}\right\|_{2} + \left\|\frac{\partial}{\partial \boldsymbol{u}_{j}(\boldsymbol{s})}\sum_{p=1}^{n}g\left(\boldsymbol{w},\boldsymbol{a},\boldsymbol{z}_{p}\right)\right\|_{2}$$
(21)

Upon expansion,

$$\left\| \frac{\partial}{\partial \boldsymbol{u}_{j}(s)} \sum_{p=1}^{n} g\left(\boldsymbol{w}, \boldsymbol{a}, \boldsymbol{z}_{p}\right) \right\|_{2}$$

$$= \left\| \sum_{p=1}^{n} \sum_{r=1}^{m} \frac{1}{\sqrt{m}} \boldsymbol{a}_{r} \boldsymbol{1}_{\{\boldsymbol{w}_{r}\boldsymbol{z}_{p} \geq 0\}} \boldsymbol{w}_{r} \frac{1}{\sqrt{m}} \boldsymbol{v}_{j} \boldsymbol{1}_{\{\boldsymbol{v}_{j}^{T} \boldsymbol{x}_{p} \geq 0\}} \boldsymbol{x}_{p} \right\|_{2}$$

$$(22)$$

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# Reaction With Diffusion: Diffusion Term

By triangle inequality, Cauchy-Schwarz inequality, and Lemma 3, we get

$$\left\| \frac{\partial}{\partial \boldsymbol{u}_{j}(s)} \sum_{p=1}^{n} g\left(\boldsymbol{w}, \boldsymbol{a}, \boldsymbol{z}_{p}\right) \right\|_{2} \leq \frac{1}{m} \sum_{p=1}^{n} \left\| \boldsymbol{v}_{j} \boldsymbol{1}_{\left\{\boldsymbol{v}_{j}^{T} \boldsymbol{x}_{p} \geq 0\right\}} \boldsymbol{x}_{p} \sum_{r=1}^{m} \boldsymbol{a}_{r} \boldsymbol{w}_{r} \boldsymbol{1}_{\left\{\boldsymbol{w}_{r} \boldsymbol{z}_{p} \geq 0\right\}} \right\|_{2}$$

$$\leq \frac{1}{m} \sum_{p=1}^{n} \left\| \sum_{r=1}^{m} \boldsymbol{u}_{r} \right\|_{2} \sqrt{2 \log \left(\frac{2}{\delta}\right)}$$

$$\leq \frac{\ln \sqrt{2 \log \left(\frac{2}{\delta}\right)}}{m} = \mathcal{O}\left(\frac{\mu}{\sqrt{m}}\right)$$
(23)

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Reaction Dynamics:

$$\mathfrak{R}_{j}^{u}(\boldsymbol{u}_{j}(t)) \leq \frac{\sqrt{n}}{\sqrt{m}} \left( \|\boldsymbol{z}(0) - \boldsymbol{y}\|_{2} - \kappa \mu \right) \exp\left(-\frac{\lambda_{0}}{2}t\right) + \frac{\sqrt{n}}{\sqrt{m}} \kappa \mu.$$
(24)

Diffusion Dynamics:

$$\mathfrak{D}_{j}^{u}(\boldsymbol{u}_{j}(t)) \leq \frac{Ln\sqrt{2\log\left(\frac{2}{\delta}\right)}}{m}.$$
(25)

Integrating over  $0 \le s \le t$ ,

$$\begin{aligned} \|\boldsymbol{u}_{j}(t) - \boldsymbol{u}_{j}(0)\|_{2} &\leq \int_{0}^{t} \left\| \frac{d\boldsymbol{u}_{j}(s)}{ds} \right\|_{2} ds \\ &\leq \int_{0}^{t} \mathfrak{R}_{j}^{u}(\boldsymbol{u}_{j}(s)) + \mathfrak{D}_{j}^{u}(\boldsymbol{u}_{j}(s)) ds. \end{aligned}$$
(26)

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#### Individual Neuron

$$\|\boldsymbol{u}_{j}(t) - \boldsymbol{u}_{j}(0)\|_{2} \leq \mathcal{O}\left(\frac{n^{3/2}}{m^{1/2}\lambda_{0}\delta} + \left(\frac{\mu(1+\kappa\sqrt{n})}{m^{1/2}}\right)t\right)$$

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#### Individual Neuron

$$\|\boldsymbol{u}_{j}(t) - \boldsymbol{u}_{j}(0)\|_{2} \leq \mathcal{O}\left(\frac{n^{3/2}}{m^{1/2}\lambda_{0}\delta} + \left(\frac{\mu(1+\kappa\sqrt{n})}{m^{1/2}}\right)t\right)$$

#### Spatial Grid of Neurons

$$\| \boldsymbol{U}(t) - \boldsymbol{U}(0) \|_{F} \leq \mathcal{O}\left( \frac{n^{3/2}}{\lambda_{0}\delta} + \mu \left( 1 + \kappa \sqrt{n} \right) t \right)$$

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Pseudo-Reaction-Diffusion Model

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#### Individual Neuron

$$\|\boldsymbol{u}_{j}(t) - \boldsymbol{u}_{j}(0)\|_{2} \leq \mathcal{O}\left(\frac{n^{3/2}}{m^{1/2}\lambda_{0}\delta} + \left(\frac{\mu(1+\kappa\sqrt{n})}{m^{1/2}}\right)t\right)$$

#### Spatial Grid of Neurons

$$\|oldsymbol{U}(t) - oldsymbol{U}(0)\|_F \leq \mathcal{O}\left(rac{n^{3/2}}{\lambda_0\delta} + \mu\left(1 + \kappa\sqrt{n}
ight)t
ight)$$

Breakdown Threshold

$$m = \Omega\left(\left(\frac{n^{7/2}}{\lambda_0^2\delta^2} + \frac{n^2\mu(1+\kappa\sqrt{n})\tau_0}{\lambda_0\delta}\right)^2\right)$$

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# Jointly Training Both Layers

#### Theorem (Reaction-Diffusion Dynamics)

If we absorb constants in  $\mathcal{O}(.)$  and set  $(\mathbf{y}_p - \mathbf{z}_p)_i v_{ij} \mathbf{1}_{\{\mathbf{u}_j^T \mathbf{x}_p \ge 0\}} \mathbf{x}_{p,k} = \mathcal{O}(1)$ for  $i \in [d_{out}]$  and  $p \in [n]$ , then for all  $j \in [m]$  the RD dynamics satisfy:

$$\begin{split} \mathfrak{R}_{j}^{\boldsymbol{u}}\left(\boldsymbol{u}_{j},\boldsymbol{v}_{j}\right) &= \mathcal{O}\left(nd_{in}\sqrt{\frac{d_{out}}{m}}\right),\\ \mathfrak{D}_{j}^{\boldsymbol{u}}\left(\nabla^{2}\boldsymbol{u}_{j}\right) &= \mathcal{O}\left(nm^{2}d_{in}d_{out}^{3/2}\right),\\ \mathfrak{R}_{j}^{\boldsymbol{v}}\left(\boldsymbol{u}_{j},\boldsymbol{v}_{j}\right) &= \mathcal{O}\left(nd_{in}\sqrt{\frac{d_{out}}{m}}\right),\\ \mathfrak{D}_{j}^{\boldsymbol{v}}\left(\nabla^{2}\boldsymbol{v}_{j}\right) &= \mathcal{O}\left(nm^{2}d_{in}d_{out}^{1/2}\right). \end{split}$$

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#### Experiments

- Linear Rate: Solution in a larger subspace around initialization.
- Theorem 1: Maintaining symmetry and homogeneity.
- Theorem 2: Breakdown of symmetry and homogeneity.

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#### Experiments

- Linear Rate: Solution in a larger subspace around initialization.
- Theorem 1: Maintaining symmetry and homogeneity.
- Theorem 2: Breakdown of symmetry and homogeneity.

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### Experimental Results: Linear Rate



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### Experimental Results: Linear Rate



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#### Experimental Results: Dissecting Diffusion



#### Experiments

- Linear Rate: Solution in a larger subspace around initialization.
- Theorem 1: Maintaining symmetry and homogeneity.
- Theorem 2: Breakdown of symmetry and homogeneity.

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# Turing Patterns by RD Model

Reaction-Diffusion Model

$$\frac{d\mathbf{u}_{j}}{dt} = \mathfrak{R}_{j}^{\boldsymbol{u}}\left(\mathbf{u}_{j}, \mathbf{v}_{j}\right) + \mathfrak{D}_{j}^{\boldsymbol{u}}\left(\nabla^{2}\mathbf{u}_{j}\right),$$
$$\frac{d\mathbf{v}_{j}}{dt} = \mathfrak{R}_{j}^{\boldsymbol{v}}\left(\mathbf{u}_{j}, \mathbf{v}_{j}\right) + \mathfrak{D}_{j}^{\boldsymbol{v}}\left(\nabla^{2}\mathbf{v}_{j}\right).$$



## Turing-like Patterns by PRD Model: Synthetic Dataset





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# Turing-like Patterns by PRD Model: MNIST



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## Turing-like Patterns by PRD Model: FashionMNIST



Pseudo-Reaction-Diffusion Model

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# Turing-like Patterns by Gray-Scott Model

Gray-Scott Model  

$$\frac{\partial u}{\partial t} = F(1-u) - uv^2 + \mu' \nabla^2 u$$

$$\frac{\partial v}{\partial t} = -(F+k)v + uv^2 + \nu' \nabla^2 v$$
Parameters  

$$F = 0.025, K = 0.055, \mu' = 2e - 5, \nu' = 1e - 5$$

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# Turing-like Patterns by Gray-Scott Model

Gray-Scott Model  

$$\frac{\partial u}{\partial t} = F(1-u) - uv^2 + \mu'\nabla^2 u$$

$$\frac{\partial v}{\partial t} = -(F+k)v + uv^2 + \nu'\nabla^2 v$$
Parameters  

$$F = 0.025, K = 0.060, \mu' = 2e - 5, \nu' = 1e - 5$$

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# Importance of Diffusion in PRD Model

- Reminiscent of patterns observed in nature
- Interpretable kernel weights
- Feature visualization:

$$\delta_{j} = \arg \max_{\delta \in \Delta} \boldsymbol{u}_{j}^{T} \left( x + \delta \right)$$







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Pseudo-Reaction-Diffusion Model

## Summary

- Exponentially fast convergence of over-parameterized networks under adversarial interaction.
- Theoretical justification of symmetry and homogeneity.
- Exploration of larger subspace around initialization beyond breakdown of symmetry and homogeneity.
- Interpretable kernels in regularized adversarial learning.
- Turing-like pattern formation under mild diffusion.
- Resemblance with naturally occurring Bernoulli differential equation.

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